

**5. // Solve the following boundary value problem**

$$\frac{d^2y}{dt^2} + 9y = \cos t \text{ where } y(0) = 1 \text{ and } y\left(\frac{\pi}{2}\right) = 2.$$

[CP 2016 Type]

**Solution** Here the given differential equation is

$$\frac{d^2y}{dt^2} + 9y = \cos t \quad \dots (1)$$

Taking Laplace transform of both sides of (1) we have,

$$L\left\{\frac{d^2y}{dt^2} + 9y\right\} = L\{\cos t\}$$

$$\text{or, } L\left\{\frac{d^2y}{dt^2}\right\} + 9L\{y\} = \frac{p}{1+p^2}$$

$$\text{or, } p^2L\{y\} - py(0) - \frac{dy}{dt}\Big|_{t=0} + 9\bar{y} = \frac{p}{1+p^2} \quad [\text{where } \bar{y} = L\{y\}]$$

$$\text{or, } (p^2 + 9)\bar{y} - p \cdot 1 - c = \frac{p}{1+p^2} \text{ since } y(0) = 1 \text{ and } \frac{dy}{dt}\Big|_{t=0} = c, \text{ say}$$

$$\text{or, } \bar{y} = \frac{c+p}{9+p^2} + \frac{p}{(1+p^2)(9+p^2)} = \frac{p}{9+p^2} + \frac{c}{3} \cdot \frac{3}{9+p^2} + \frac{1}{8} \left[ \frac{p}{1+p^2} - \frac{p}{9+p^2} \right]$$

Taking inverse Laplace transform of both sides, we have,

$$\begin{aligned} y(t) &= L^{-1}\left\{\frac{p}{9+p^2}\right\} + \frac{c}{3} L^{-1}\left\{\frac{3}{9+p^2}\right\} + \frac{1}{8} \left[ L^{-1}\left\{\frac{p}{1+p^2}\right\} - L^{-1}\left\{\frac{p}{9+p^2}\right\} \right] \\ &= \cos 3t + \frac{c}{3} \sin 3t + \frac{1}{8} (\cos t - \cos 3t) \\ &= \frac{1}{8} \cos t + \frac{7}{8} \cos 3t + \frac{c}{3} \sin 3t \quad \dots (2) \end{aligned}$$

To determine  $c$ , substituting  $t = \frac{\pi}{2}$  and noting  $y\left(\frac{\pi}{2}\right) = 2$ , we have,

$$y\left(\frac{\pi}{2}\right) = 2 = \frac{1}{8} \cos\left(\frac{\pi}{2}\right) + \frac{7}{8} \cos\left(\frac{3\pi}{2}\right) + \frac{c}{3} \sin\left(\frac{3\pi}{2}\right)$$

$$\text{or, } -\frac{c}{3} = 2 \text{ giving } c = -6.$$

Hence putting  $c = -6$  in (2), the required solution becomes :

$$y(t) = \frac{1}{8} \cos t + \frac{7}{8} \cos 3t - 2 \sin 3t.$$

**6. // Solve the equation  $\frac{d^2x}{dt^2} + \lambda^2 x = a \cos \omega t$ ; given that  $x = c_0$  and  $\frac{dx}{dt} = c_1$  when  $t = 0$ .**

**Solution** Here the given differential equation is

$$\frac{d^2x}{dt^2} + \lambda^2 x = a \cos \omega t \quad \dots (1)$$

Taking Laplace transform of the both sides of (1) we have,

$$\begin{aligned} L\left\{\frac{d^2x}{dt^2} + \lambda^2 x\right\} &= L\{a \cos \omega t\} \quad \text{or, } L\left\{\frac{d^2x}{dt^2}\right\} + \lambda^2 L\{x\} = \frac{ap}{\omega^2 + p^2} \\ \text{or, } p^2 L\{x\} - px(0) - \frac{dx}{dt}\Big|_{t=0} + \lambda^2 \bar{x} &= \frac{ap}{\omega^2 + p^2} \quad [\text{where } \bar{x} = L\{x(t)\}] \\ \text{or, } p^2 \bar{x} + \lambda^2 \bar{x} - p \cdot c_0 - c_1 &= \frac{ap}{\omega^2 + p^2} \quad [\text{using the initial conditions}] \\ \text{or, } (\lambda^2 + p^2) \bar{x} &= \frac{ap}{\omega^2 + p^2} + (pc_0 + c_1) \\ \text{or, } \bar{x} &= \frac{ap}{(\lambda^2 + p^2)(\omega^2 + p^2)} + \frac{pc_0 + c_1}{\lambda^2 + p^2} = c_0 \frac{p}{\lambda^2 + p^2} + \frac{c_1}{\lambda} \cdot \frac{\lambda}{\lambda^2 + p^2} + \frac{a}{\lambda^2 - \omega^2} \left( \frac{p}{\omega^2 + p^2} - \frac{p}{\lambda^2 + p^2} \right) \end{aligned}$$

Taking inverse Laplace transform from both sides, we have,

$$\begin{aligned} x(t) &= c_0 L^{-1}\left\{\frac{p}{\lambda^2 + p^2}\right\} + \frac{c_1}{\lambda} L^{-1}\left\{\frac{\lambda}{\lambda^2 + p^2}\right\} + \frac{a}{\lambda^2 - \omega^2} L^{-1}\left\{\frac{p}{\omega^2 + p^2} - \frac{p}{\lambda^2 + p^2}\right\} \\ &= c_0 \cos \lambda t + \frac{c_1}{\lambda} \sin \lambda t + \frac{a}{\lambda^2 - \omega^2} (\cos \omega t - \cos \lambda t) \end{aligned}$$

which is the required solution of the given differential equation.

**Q. Solve using Laplace transform  $(D^2 + 4)y = 4$  given that  $y = 1$  and  $Dy = 5$  when  $t = 0$  ( $D \equiv \frac{d}{dt}$ ).** [CP 2004, 2013]

**Solution** Here the given differential equation is :

$$(D^2 + 4)y = 4 \quad \dots (1)$$

Taking Laplace transform of (1) we have,

$$L\{(D^2 + 4)y\} = L\{4\}$$

$$\text{or, } L\{D^2 y\} + 4L\{y\} = \frac{4}{p}$$

$$\text{or, } p^2 L\{y\} - py(0) - \frac{dy}{dt}\Big|_{t=0} + 4L\{y\} = \frac{4}{p}$$

$$\text{or, } (p^2 + 4)L\{y\} - p \cdot 1 - 5 = \frac{4}{p} \quad [\text{using initial conditions}]$$

$$\text{or, } (p^2 + 4)L\{y\} = \frac{4}{p} + p + 5$$

$$\text{or, } L\{y\} = \frac{4}{p(p^2 + 4)} + \frac{p+5}{p^2+4}$$

Taking inverse Laplace transform, we have

$$\begin{aligned} y(t) &= L^{-1}\left\{\frac{4}{p(p^2 + 4)} + \frac{p+5}{p^2+4}\right\} = L^{-1}\left\{\frac{1}{p} - \frac{p}{p^2+4} + \frac{p+5}{p^2+4}\right\} \\ &= L^{-1}\left\{\frac{1}{p}\right\} + \frac{5}{2} L^{-1}\left\{\frac{2}{p^2+4}\right\} = 1 + \frac{5}{2} \sin 2t \end{aligned}$$

which is the required solution.

**8. // Solve  $\frac{d^2y}{dt^2} + 3\frac{dy}{dt} + 2y = e^{-t}$ , given  $y(0) = 0 = y'(0)$  using Laplace transformation method.** [CP 2017]

**Solution** Here the given differential equation is

$$\frac{d^2y}{dt^2} + 3\frac{dy}{dt} + 2y = e^{-t} \quad \dots (1)$$

Taking Laplace transform of both sides of (1) we have,

$$L\left\{\frac{d^2y}{dt^2} + 3\frac{dy}{dt} + 2y\right\} = L\{e^{-t}\}$$

$$\text{or, } L\left\{\frac{d^2y}{dt^2}\right\} + 3L\left\{\frac{dy}{dt}\right\} + 2L\{y\} = \frac{1}{p+1}$$

$$\text{or, } p^2L\{y\} - py(0) - y'(0) + 3[pL\{y\} - y(0)] + 2L\{y\} = \frac{1}{p+1}$$

$$\text{or, } (p^2 + 3p + 2)L\{y\} - p \cdot 0 - 0 = \frac{1}{p+1} \quad [\text{using initial conditions}]$$

$$\text{or, } L\{y\} = \frac{1}{(p+1)(p^2 + 3p + 2)} = \frac{1}{(p+1)^2(p+2)}$$

Taking inverse Laplace transform, we have,

$$y(t) = L^{-1}\left\{\frac{1}{(p+1)^2(p+2)}\right\} = L^{-1}\left\{\frac{1}{(p+1)^2} - \frac{1}{(p+1)(p+2)}\right\}$$

$$= L^{-1}\left\{\frac{1}{(p+1)^2} - \frac{1}{p+1} + \frac{1}{p+2}\right\} = L^{-1}\left\{\frac{1}{(p+1)^2}\right\} - L^{-1}\left\{\frac{1}{p+1}\right\} + L^{-1}\left\{\frac{1}{p+2}\right\}$$

$$= te^{-t} - e^{-t} + e^{-2t} = (t-1)e^{-t} + e^{-2t}$$

Hence the required solution is :

$$y(t) = (t-1)e^{-t} + e^{-2t}.$$

**9. // Solve by Laplace transformation :**

$$(D^2 + D)x = 2, x(0) = 3, x'(0) = 1, D \equiv \frac{d}{dt}. \quad [\text{CP 2018}]$$

**Solution** Here the given differential equation is :

$$(D^2 + D)x = 2$$

Taking Laplace transform of both sides of (1), we have,

$$L\{(D^2 + D)x\} = L\{2\}$$

$$\text{or, } L\{D^2x\} + L\{Dx\} = \frac{2}{p}$$

$$\text{or, } p^2L\{x\} - px(0) - x'(0) + pL\{x\} - x(0) = \frac{2}{p}$$

$$\text{or, } (p^2 + p)L\{x\} - p \cdot 3 - 1 - 3 = \frac{2}{p} \quad [\text{Using initial conditions}]$$

$$\text{or, } (p^2 + p)L\{x\} = \frac{2}{p} + 3p + 4 = \frac{3p^2 + 4p + 2}{p}$$

$$\text{or, } L\{x\} = \frac{3p^2 + 4p + 2}{p^2(p+1)} = \frac{3}{p+1} + \frac{4}{p(p+1)} + \frac{2}{p^2(p+1)}$$

Taking inverse Laplace transform of both sides, we have,

$$\begin{aligned} x(t) &= L^{-1}\left\{\frac{3p^2 + 4p + 2}{p^2(p+1)}\right\} = L^{-1}\left\{\frac{3}{p+1} + \frac{4}{p(p+1)} + \frac{2}{p^2(p+1)}\right\} \\ &= L^{-1}\left\{\frac{3}{p+1} + \frac{4}{p} - \frac{4}{p+1} + \frac{2}{p^2} - \frac{2}{p(p+1)}\right\} \\ &= L^{-1}\left\{\frac{2}{p^2} + \frac{4}{p} - \frac{1}{p+1} - \frac{2}{p} + \frac{2}{p+1}\right\} = L^{-1}\left\{\frac{2}{p^2} + \frac{2}{p} + \frac{1}{p+1}\right\} \\ &= L^{-1}\left\{\frac{2}{p^2}\right\} + L^{-1}\left\{\frac{2}{p}\right\} + L^{-1}\left\{\frac{1}{p+1}\right\} \\ &= 2t + 2 + e^{-t} \end{aligned}$$

Hence the required solution is :  $x(t) = 2t + 2 + e^{-t}$ .

**10.** Solve the initial value problem :  $(D^2 - 3D + 2)y = 1 - e^{2t}$ , where  $y = 1$  and  $Dy = 0$  when  $t = 0$  and  $D \equiv \frac{d}{dt}$ .

**Solution** Here the given differential equation is

$$(D^2 - 3D + 2)y = 1 - e^{2t}, D \equiv \frac{d}{dt} \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$L\{(D^2 - 3D + 2)y\} = L\{1 - e^{2t}\}$$

$$\text{or, } L\{D^2y\} - 3L\{Dy\} + 2L\{y\} = L\{1\} - L\{e^{2t}\}$$

$$\text{or, } p^2L\{y\} - py(0) - Dy(0) - 3[pL\{y\} - y(0)] + 2L\{y\} = \frac{1}{p} - \frac{1}{p-2}$$

$$\text{or, } (p^2 - 3p + 2)\bar{y} - p \cdot 1 - 0 + 3 \cdot 1 = -\frac{2}{p(p-2)} \quad [\text{using initial conditions and } \bar{y} = L\{y\}]$$

$$\text{or, } (p-1)(p-2)\bar{y} = p-3 - \frac{2}{p(p-2)} = \frac{p^3 - 5p^2 + 6p - 2}{p(p-2)} = \frac{(p-1)(p^2 - 4p + 2)}{p(p-2)}$$

$$\text{or, } \bar{y} = \frac{p^2 - 4p + 2}{p(p-2)^2} = \frac{1}{2p} + \frac{1}{2(p-2)} - \frac{1}{(p-2)^2}$$

Taking inverse Laplace transform from the both sides we have,

$$y = L^{-1}\left\{\frac{1}{2p}\right\} + \frac{1}{2} L^{-1}\left\{\frac{1}{p-2}\right\} - L^{-1}\left\{\frac{1}{(p-2)^2}\right\}$$

i.e.,  $y(t) = \frac{1}{2} + \frac{1}{2}e^{2t} - te^{2t}$ , which is the required solution of the given differential equation.

- 11.** // Using Laplace transform, solve the equation  $\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = 4e^{2x}$  when  $y(0) = -3$  and  $\left(\frac{dy}{dx}\right)_{x=0} = 5$ . [CP 2014, 2013, 2009]

**Solution** Here the given differential equation is :

$$\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = 4e^{2x} \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$\begin{aligned} L\left\{\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y\right\} &= L\{4e^{2x}\} \quad \text{or, } L\left\{\frac{d^2y}{dx^2}\right\} - 3L\left\{\frac{dy}{dx}\right\} + 2L\{y\} = \frac{4}{p-2} \\ \text{or, } \left[p^2L\{y\} - py(0) - \left(\frac{dy}{dx}\right)_{x=0}\right] - 3[pL\{y\} - y(0)] + 2L\{y\} &= \frac{4}{p-2} \\ \text{or, } (p^2 - 3p + 2)L\{y\} - (p-3)(-3) - 5 &= \frac{4}{p-2} \quad [\text{using initial conditions}] \\ \text{or, } (p-1)(p-2)L\{y\} &= \frac{4}{p-2} + 5 - 3(p-3) = \frac{4}{p-2} - 3p + 14 \\ \text{or, } L\{y\} &= \frac{4}{(p-1)(p-2)^2} - \frac{3p}{(p-1)(p-2)} + \frac{14}{(p-1)(p-2)} \\ &= \frac{4}{(p-2)^2} - \frac{4}{(p-1)(p-2)} + \frac{14}{(p-1)(p-2)} - \frac{3}{2} \cdot \frac{(p-1)+(p-2)+3}{(p-1)(p-2)} \\ &= \frac{4}{(p-2)^2} - \frac{10}{(p-1)(p-2)} - \frac{3}{2} \cdot \frac{1}{p-2} - \frac{3}{2} \cdot \frac{1}{p-1} - \frac{9}{2} \cdot \frac{1}{(p-1)(p-2)} \\ &= \frac{4}{(p-2)^2} - \frac{3}{2} \left( \frac{1}{p-1} + \frac{1}{p-2} \right) - \frac{29}{2} \left( \frac{1}{p-2} - \frac{1}{p-1} \right) \\ &= \frac{4}{(p-2)^2} - \frac{16}{p-2} + \frac{13}{p-1} \end{aligned}$$

Taking inverse Laplace transform, we have

$$y(t) = L^{-1}\left\{\frac{4}{(p-2)^2} - \frac{16}{p-2} + \frac{13}{p-1}\right\}$$

$$= 4te^{2t} - 16e^{2t} + 13e^t = 4e^{2t}(t-4) + 13e^t$$

which is the required solution.

- 12.** // Solve using Laplace transformation, the equation  $\frac{d^2y}{dt^2} + y = \sin 3t$  when  $y(0) = 0$ ,  $\left(\frac{dy}{dt}\right)_{t=0} = 0$ . [CP 2014]

**Solution** Here the given differential equation is

$$\frac{d^2y}{dt^2} + y = \sin 3t \quad \dots (1)$$

Taking Laplace transform both sides of (1) we have,

$$L\left\{\frac{d^2y}{dt^2} + y\right\} = L\{\sin 3t\}$$

$$\text{or, } L\left\{\frac{d^2y}{dt^2}\right\} + L\{y\} = \frac{3}{p^2+9}$$

$$\text{or, } p^2 L\{y\} - py(0) - \left(\frac{dy}{dt}\right)_{t=0} + L\{y\} = \frac{3}{p^2+9}$$

$$\text{or, } (p^2 + 1)L\{y\} = \frac{3}{p^2+9} \quad [\text{since } y(0) = \left(\frac{dy}{dt}\right)_{t=0} = 0, \text{ given}]$$

$$\text{or, } L\{y\} = \frac{3}{(p^2+1)(p^2+9)}$$

Taking inverse Laplace transform of both sides, we have,

$$\begin{aligned} y(t) &= L^{-1}\left\{\frac{3}{(p^2+1)(p^2+9)}\right\} = L^{-1}\left\{\frac{3}{8}\left(\frac{1}{p^2+1} - \frac{1}{p^2+9}\right)\right\} = \frac{3}{8}L^{-1}\left\{\frac{1}{p^2+1}\right\} - \frac{1}{8}L^{-1}\left\{\frac{3}{p^2+9}\right\} \\ &= \frac{3}{8}\sin t - \frac{1}{8}\sin 3t = \frac{1}{8}(3\sin t - \sin 3t), \end{aligned}$$

which is the required solution.

### 13. // Solve the initial value problem using Laplace transform :

$$\frac{d^2x}{dt^2} + 4x = \sin 3t, x(0) = 0 \text{ and } x'(0) = 0.$$

Solution Here the given differential equation is

$$\frac{d^2x}{dt^2} + 4x = \sin 3t \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$L\left\{\frac{d^2x}{dt^2}\right\} + 4L\{x\} = L\{\sin 3t\}$$

$$\text{or, } p^2 L\{x\} - px(0) - x'(0) + 4L\{x\} = \frac{3}{p^2+(3)^2}$$

$$\text{or, } (p^2 + 4)\bar{x} - p \cdot 0 - 0 = \frac{3}{p^2+9} \quad [\text{where } \bar{x} = L\{x\} \text{ and since } x(0) = x'(0) = 0]$$

$$\text{or, } \bar{x} = \frac{3}{(p^2+4)(p^2+9)} = \frac{3}{5}\left[\frac{1}{p^2+4} - \frac{1}{p^2+9}\right]$$

Taking inverse Laplace transform of both sides, we have,

$$\begin{aligned} x(t) &= \frac{3}{5}\left[L^{-1}\left\{\frac{1}{p^2+4}\right\} - L^{-1}\left\{\frac{1}{p^2+9}\right\}\right] = \frac{3}{5}\left[\frac{1}{2}\sin 2t - \frac{1}{3}\sin 3t\right] \\ &= \frac{1}{10}[3\sin 2t - 2\sin 3t] \end{aligned}$$

which is the required solution of the given differential equation.

**14.** // Solve the boundary value problem :

$(D + 1)^2 y = t$ , given that  $y = -3$ , when  $t = 0$  and  $y = -1$  when  $t = 1$  and  $D \equiv \frac{d}{dt}$ .  
[CP 2020]

**Solution** Here the given differential equation is :

$$(D + 1)^2 y = t \text{ i.e., } (D^2 + 2D + 1)y = t \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$\begin{aligned} L\{D^2y\} + 2L\{Dy\} + L\{y\} &= L\{t\} \\ \text{or, } [p^2L\{y\} - py(0) - y'(0)] + 2[pL\{y\} - y(0)] + L\{y\} &= \frac{1}{p^2} \end{aligned}$$

$$\text{or, } (p^2 + 2p + 1)\bar{y} - p \cdot (-3) - C - 2 \cdot (-3) = \frac{1}{p^2}$$

where  $\bar{y} = L\{y\}$ ,  $y'(0) = c$ , say and  $y(0) = -3$ , given

$$\text{or, } (p + 1)^2 \bar{y} = \frac{1}{p^2} + c - 6 - 3p.$$

$$\text{or, } \bar{y} = \frac{1}{p^2(p+1)^2} + \frac{c}{(p+1)^2} - \frac{3p+6}{(p+1)^2} \quad \dots (2)$$

Taking inverse Laplace transform of both sides of (2), we have,

$$\begin{aligned} y &= L^{-1}\left\{\frac{1}{p^2(p+1)^2}\right\} + L^{-1}\left\{\frac{c}{(p+1)^2}\right\} - L^{-1}\left\{\frac{3p+6}{(p+1)^2}\right\} \\ &= L^{-1}\left\{\frac{1}{(p+1)^2} + \frac{1}{p^2} + \frac{2}{p+1} - \frac{2}{p}\right\} + cL^{-1}\left\{\frac{1}{(p+1)^2}\right\} - L^{-1}\left\{\frac{3}{p+1}\right\} - L^{-1}\left\{\frac{3}{(p+1)^2}\right\} \\ &= L^{-1}\left\{\frac{1}{p^2}\right\} - L^{-1}\left\{\frac{2}{p}\right\} - L^{-1}\left\{\frac{1}{p+1}\right\} + (c-2)L^{-1}\left\{\frac{1}{(p+1)^2}\right\} \\ &= t - 2 - e^{-t}L^{-1}\left\{\frac{1}{p}\right\} + (c-2)e^{-t}\left\{\frac{1}{p^2}\right\} \\ &= t - 2 - e^{-t} \cdot 1 + (c-2) \cdot e^{-t} \cdot t \\ &= t - e^{-t} + (c-2)te^{-t} - 2 \quad \dots (3) \end{aligned}$$

Using the boundary condition  $y = -1$  when  $t = 1$ , we have from (3),

$$-1 = 1 - e^{-1} + (c-2)e^{-1} - 2$$

or,  $c-2 = 1$  giving  $c = 3$ .

substituting  $c = 3$  in (3); we have the required solution as

$$y(t) = t - e^{-t} + (3-2)te^{-t} - 2 \text{ i.e., } y(t) = e^{-t}(t-1) + t - 2$$

**15.** // Solve by using Laplace transformation, the equation  $\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 5y = e^{-t}\sin t$ , given that when  $t = 0$ ,  $y = 0$  and  $\frac{dy}{dt} = 0$ .  
[CP 2016, 2008]

**Solution** Here the given differential equation is

$$\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 5y = e^{-t}\sin t \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$L\left\{\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 5y\right\} = L\{e^{-t}\sin t\} \quad \text{or, } L\left\{\frac{d^2y}{dt^2}\right\} + 2\left\{\frac{dy}{dt}\right\} + 5L(y) = \frac{1}{(p+1)^2 + 1}$$

$$\text{or, } [p^2L(y) - py(0) - \frac{dy}{dt}]_{t=0} + 2[pL(y) - y(0)] + 5L(y) = \frac{1}{p^2 + 2p + 2}$$

$$\text{or, } (p^2 + 2p + 5)L(y) = \frac{1}{p^2 + 2p + 2} \quad [\text{using initial conditions}]$$

$$\text{or, } L(y) = \frac{1}{(p^2 + 2p + 2)(p^2 + 2p + 5)}$$

Taking inverse Laplace transform, we have,

$$y(t) = L^{-1}\left\{\frac{1}{(p^2 + 2p + 2)(p^2 + 2p + 5)}\right\} = \frac{1}{3}L^{-1}\left\{\frac{1}{(p+1)^2 + 1} - \frac{1}{(p+1)^2 + 4}\right\}$$

$$= \frac{e^{-t}}{3} \left[ L^{-1}\left\{\frac{1}{p^2 + 1}\right\} - L^{-1}\left\{\frac{1}{p^2 + 4}\right\} \right] \quad [\text{using first shifting property}]$$

$$= \frac{e^{-t}}{3} \left[ \sin t - \frac{\sin 2t}{2} \right] = \frac{e^{-t}}{6} [2\sin t - \sin 2t]$$

which is the required solution.

## 16. / Solve the initial value problem using Laplace transform :

$$(D^2 + 2D + 5)y = e^{-t}\sin t, y(0) = 0, y'(0) = 1 \text{ and } D \equiv \frac{d}{dt}.$$

**Solution** Here the given differential equation is

$$(D^2 + 2D + 5)y = e^{-t}\sin t \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$L\{D^2y\} + 2L\{Dy\} + 5L(y) = L\{e^{-t}\sin t\}$$

$$\text{or, } [p^2L(y) - py(0) - y'(0)] + 2[pL(y) - y(0)] + 5L(y) = \frac{1}{1+(p+1)^2} \quad [\text{using first shifting property}]$$

$$\text{or, } (p^2 + 2p + 5)\bar{y} - p \cdot 0 - 1 - 2 \cdot 0 = \frac{1}{p^2 + 2p + 2} \quad [\text{using initial conditions and } \bar{y} = L(y)]$$

$$\text{or, } (p^2 + 2p + 5)\bar{y} = 1 + \frac{1}{p^2 + 2p + 2} = \frac{p^2 + 2p + 3}{p^2 + 2p + 2}$$

$$\text{or, } \bar{y} = \frac{p^2 + 2p + 3}{(p^2 + 2p + 2)(p^2 + 2p + 5)} = \frac{(p+1)^2 + 2}{((p+1)^2 + 1)((p+1)^2 + 4)}$$

Taking inverse Laplace transform of both sides, we have,

$$y(t) = L^{-1}\left\{\frac{(p+1)^2 + 2}{((p+1)^2 + 1)((p+1)^2 + 4)}\right\} = e^{-t}L^{-1}\left\{\frac{p^2 + 2}{(p^2 + 1)(p^2 + 4)}\right\} \quad [\text{using first shifting property}]$$

$$= e^{-t}L^{-1}\left\{\frac{1}{3}\left(\frac{1}{p^2 + 1} + \frac{2}{p^2 + 4}\right)\right\} = \frac{e^{-t}}{3} \left[ L^{-1}\left\{\frac{1}{p^2 + 1}\right\} + L^{-1}\left\{\frac{2}{p^2 + 4}\right\} \right] = \frac{e^{-t}}{3} (\sin t + \sin 2t)$$

Hence the required solution of the given differential equation is  $y(t) = \frac{e^{-t}}{3} (\sin t + \sin 2t)$

**17.** // Solve  $\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + y = 3te^{-t}$ , given that  $y(0) = 4$  and  $y'(0) = 2$  by Laplace transformation. [CP 2018]

**Solution** Here the given differential equation is :

$$\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + y = 3te^{-t} \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$L\left\{\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + y\right\} = L\{3te^{-t}\}$$

$$\text{or, } L\left\{\frac{d^2y}{dt^2}\right\} + 2L\left\{\frac{dy}{dt}\right\} + L\{y\} = \frac{3}{(p+1)^2} \quad [\text{using first shifting property}]$$

$$\text{or, } p^2L\{y\} - py(0) - y'(0) + 2(pL\{y\} - y(0)) + L\{y\} = \frac{3}{(p+1)^2}$$

$$\text{or, } (p^2 + 2p + 1)\bar{y} - p \cdot 4 - 2 - 2 \cdot 4 = \frac{3}{(p+1)^2} \quad [\text{using initial conditions and } \bar{y} = L\{y\}]$$

$$\text{or, } (p+1)^2\bar{y} = \frac{3}{(p+1)^2} + 4p + 10$$

$$\text{or, } \bar{y} = \frac{3}{(p+1)^4} + \frac{4p}{(p+1)^2} + \frac{10}{(p+1)^2}$$

Taking inverse Laplace transform both sides, we have,

$$y(t) = L^{-1}\left\{\frac{3}{(p+1)^4} + \frac{4p}{(p+1)^2} + \frac{10}{(p+1)^2}\right\} = L^{-1}\left\{\frac{3}{(p+1)^4} + \frac{4}{p+1} + \frac{6}{(p+1)^2}\right\}$$

$$= L^{-1}\left\{\frac{3}{(p+1)^4}\right\} + L^{-1}\left\{\frac{6}{(p+1)^2}\right\} = e^{-t} \quad [\text{involves in constant + shifted}]$$

$$= e^{-t}L^{-1}\left\{\frac{3}{p^4} + \frac{6}{p^2} + \frac{4}{p}\right\} \quad [\text{using first shifting property}]$$

$$= e^{-t}\left[\frac{t^3}{2} + 6t + 4\right] = \frac{e^{-t}}{2}[t^3 + 12t + 8]$$

which is the required solution.

**18.** // Solve the following differential equation by Laplace transform :

$$\frac{d^2y}{dt^2} - 2\frac{dy}{dt} - 3y = t \cos t; \text{ given that } y(0) = 0 = y'(0).$$

**Solution** Here the given differential equation is

$$\frac{d^2y}{dt^2} - 2\frac{dy}{dt} - 3y = t \cos t \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$L\left\{\frac{d^2y}{dt^2}\right\} - 2L\left\{\frac{dy}{dt}\right\} - 3L\{y\} = L\{t \cos t\}$$

$$\text{or, } p^2 L\{y\} - py(0) - y'(0) - 2pL\{y\} + y(0) - 3L\{y\} = - \frac{d}{dp} [L\{\cos t\}]$$

$$\text{or, } (p^2 - 2p - 3)\bar{y} - p \cdot 0 - 0 + 0 = - \frac{d}{dp} \left\{ \frac{p}{1+p^2} \right\} \quad [\text{using initial conditions and } \bar{y} = L\{y\}]$$

$$\text{or, } (p+1)(p-3)\bar{y} = \frac{p^2-1}{(1+p^2)^2}$$

$$\text{or, } \bar{y} = \frac{p-1}{(p-3)(p^2+1)^2} = \frac{1}{50} \cdot \frac{1}{p-3} - \frac{3}{50} \cdot \frac{1}{p^2+1} - \frac{1}{50} \cdot \frac{p}{p^2+1} + \frac{2}{5} \cdot \frac{1}{(p^2+1)^2} - \frac{1}{5} \cdot \frac{p}{(p^2+1)^2}$$

Taking inverse Laplace transform from both sides, we have,

$$y(t) = \frac{1}{50} L^{-1}\left\{\frac{1}{p-3}\right\} - \frac{3}{50} L^{-1}\left\{\frac{1}{p^2+1}\right\} - \frac{1}{50} L^{-1}\left\{\frac{p}{p^2+1}\right\} + \frac{2}{5} L^{-1}\left\{\frac{1}{(p^2+1)^2}\right\} \\ - \frac{1}{5} L^{-1}\left\{\frac{p}{(p^2+1)^2}\right\} \quad \dots (2)$$

We know that,  $L^{-1}\left\{\frac{1}{p^2+1}\right\} = \sin t$  and  $L^{-1}\left\{\frac{p}{p^2+1}\right\} = \cos t$ .

$$\text{Also } L^{-1}\left\{\frac{p}{(p^2+1)^2}\right\} = \frac{t \sin t}{2}$$

To find  $L^{-1}\left\{\frac{1}{(p^2+1)^2}\right\}$  by convolution theorem, we have,

$$L^{-1}\left\{\frac{1}{(p^2+1)^2}\right\} = L^{-1}\left\{\frac{1}{1+p^2} \cdot \frac{1}{1+p^2}\right\} = \int_0^t \sin x \sin(t-x) dx \quad [\text{since } L^{-1}\left\{\frac{1}{1+p^2}\right\} = \sin t] \\ = \frac{1}{2} \int_0^t [\cos(2x-t) - \cos t] dx = \frac{1}{2} \left[ \frac{1}{2} \sin(2x-t) - x \cos t \right]_{x=0}^t \\ = \frac{1}{2} \left( \frac{1}{2} \sin t - t \cos t + \frac{1}{2} \sin t \right) = \frac{1}{2} (\sin t - t \cos t)$$

Using above results, we have from (2),

$$y(t) = \frac{e^{3t}}{50} - \frac{3 \sin t}{50} - \frac{\cos t}{50} + \frac{2}{5} \cdot \frac{1}{2} (\sin t - t \cos t) - \frac{1}{5} \cdot \frac{1}{2} t \sin t \\ = \frac{e^{3t}}{50} - \frac{3 \sin t}{50} - \frac{\cos t}{50} - \frac{1}{10} t \sin t + \frac{1}{5} (\sin t - t \cos t)$$

which is the required solution of the given differential equation.

### 19. / Solve the initial value problem using Laplace transform :

$$(D^2 - 1)y = a \cosh nt; \text{ given that } y(0) = 0, y'(0) = 2 \text{ where } D \equiv \frac{d}{dt}. \quad \dots (1)$$

**Solution** Here the given differential equation is

$$(D^2 - 1)y = a \cosh nt \quad \dots (1)$$

Taking Laplace transform of both sides we have,

$$L(D^2 - 1)y = L(a \cosh nt) \quad \text{or, } L(D^2 y) - L(y) = a L(\cosh nt)$$

$$\text{or, } p^2 L\{y\} - py(0) - y'(0) - L\{y\} = \frac{ap}{p^2 - n^2}$$

or,  $(p^2 - 1)\bar{y} - p \cdot 0 - 2 = \frac{ap}{p^2 - n^2}$  [using initial conditions and  $\bar{y} = L\{y\}$ ]

$$\text{or, } \bar{y} = \frac{2}{p^2 - 1} + \frac{ap}{(p^2 - n^2)(p^2 - 1)} = \frac{2}{p^2 - 1} + \frac{a}{n^2 - 1} \left\{ \frac{p}{p^2 - n^2} - \frac{p}{p^2 - 1} \right\}$$

Taking inverse Laplace transform from both sides we have,

$$\begin{aligned} y(t) &= L^{-1} \left\{ \frac{2}{p^2 - 1} \right\} + \frac{a}{n^2 - 1} \left[ L^{-1} \left\{ \frac{p}{p^2 - n^2} \right\} - L^{-1} \left\{ \frac{p}{p^2 - 1} \right\} \right] \\ &= 2 \sinh t + \frac{a}{n^2 - 1} (\cosh nt - \cosh t) \end{aligned}$$

which is the required solution of the given equation.

**20. // Using Laplace transformation, solve the following initial value problem**

$$\frac{d^2y}{dt^2} + 4y = 4H(t - 2) \text{ with } y(0) = y'(0) = 0 \text{ where } H(t - 2) \text{ is the Heaviside unit step function.}$$

**Solution** Here the given differential equation is

$$\frac{d^2y}{dt^2} + 4y = 4H(t - 2) \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have,

$$L \left\{ \frac{d^2y}{dt^2} + 4y \right\} = L\{4H(t - 2)\} \text{ or, } L \left\{ \frac{d^2y}{dt^2} \right\} + 4L\{y\} = 4L\{H(t - 2)\}$$

$$\text{or, } p^2\bar{y} - py(0) - y'(0) + 4\bar{y} = 4 \frac{e^{-2p}}{p} \quad [\text{where } \bar{y} = L\{y\}]$$

$$\text{or, } (p^2 + 4)\bar{y} - p \cdot 0 - 0 = 4 \frac{e^{-2p}}{p} \quad [\text{using the initial conditions}]$$

$$\text{or, } \bar{y} = 4 \frac{e^{-2p}}{p(p^2 + 4)}.$$

$$\text{Therefore, } y(t) = L^{-1} \left\{ 4 \frac{e^{-2p}}{p(p^2 + 4)} \right\} \quad \dots (2)$$

$$\text{Now, } L^{-1} \left\{ \frac{4}{p(p^2 + 4)} \right\} = 2L^{-1} \left\{ \frac{2}{p(p^2 + 4)} \right\} = 2 \int_0^t \sin 2t dt = 1 - \cos 2t.$$

$$\text{Hence } L^{-1} \left\{ \frac{4e^{-2p}}{p(p^2 + 4)} \right\} = [1 - \cos 2(t - 2)]H(t - 2)$$

So from (2) we have,

$$y(t) = [1 - \cos 2(t - 2)]H(t - 2) \text{ which is the required solution.}$$

**21. // Solve the following initial value problem :**

$$\frac{d^2y}{dt^2} - 3 \frac{dy}{dt} + 2y = 4t + e^{3t}; \text{ given that } y(0) = 1 \text{ and } y'(0) = -1.$$

**Solution** Here the given differential equation is

$$\frac{d^2y}{dt^2} - 3 \frac{dy}{dt} + 2y = 4t + e^{3t} \quad \dots (1)$$

Taking Laplace transform of both sides of (1) we have,

$$L\left\{\frac{d^2y}{dt^2} - 3 \frac{dy}{dt} + 2y\right\} = L\{4t + e^{3t}\}$$

$$\text{or, } L\left\{\frac{d^2y}{dt^2}\right\} - 3L\left\{\frac{dy}{dt}\right\} + 2L\{y\} = 4L\{t\} + L\{e^{3t}\}$$

$$\text{or, } [p^2L\{y\} - py(0) - y'(0)] - 3[pL\{y\} - y(0)] + 2L\{y\} = \frac{4}{p^2} + \frac{1}{p-3}$$

$$\text{or, } (p^2 - 3p + 2)\bar{y} - p \cdot 1 + 1 + 3 \cdot 1 = \frac{4p-12+p^2}{p^2(p-3)}$$

[where  $\bar{y} = L\{y\}$  and  $y(0) = 1$ ,  $y'(0) = -1$ , given]

$$\text{or, } (p-1)(p-2)\bar{y} = p-4 + \frac{(p-2)(p+6)}{p^2(p-3)}$$

$$\text{or, } \bar{y} = \frac{p-4}{(p-1)(p-2)} + \frac{p+6}{p^2(p-3)(p-1)} \quad [\text{Assuming } p \neq 2]$$

$$= \frac{3}{p-1} - \frac{2}{p-2} + \frac{p+6}{p^2(p-3)(p-1)} \quad \dots (2)$$

$$\text{Let } \frac{p+6}{p^2(p-3)(p-1)} = \frac{A}{p} + \frac{B}{p^2} + \frac{C}{p-1} + \frac{D}{p-3},$$

where A, B, C, D are four constants to be determined.

$$\text{or, } \frac{p+6}{p^2(p-3)(p-1)} = \frac{Ap(p-1)(p-3) + B(p-1)(p-3) + Cp^2(p-3) + Dp^2(p-1)}{p^2(p-3)(p-1)}$$

$$\text{or, } Ap(p-1)(p-3) + B(p-1)(p-3) + Cp^2(p-3) + Dp^2(p-1) = p+6 \quad \dots (3)$$

Putting  $p = 0$  in (3) we have,

$$3B = 6 \text{ giving } B = 2$$

Putting  $p = 1$  in (3) we have,

$$C(1-3) = 7 \text{ giving } C = -\frac{7}{2}$$

Next, putting  $p = 3$  in (3) we have,

$$18D = 9 \text{ giving } D = \frac{1}{2}$$

Finally putting  $p = 2$  in (3) we have,

$$A \cdot 2 \cdot 1 \cdot (-1) + 2 \cdot 1 \cdot (-1) - \frac{7}{2} \cdot 4 \cdot (-1) + \frac{1}{2} \cdot 4 \cdot 1 = 8$$

$$\text{or, } -2A - 2 + 14 + 2 = 8 \text{ giving } A = 3.$$

Hence from (2) we have,

$$\bar{y} = \frac{3}{p-1} - \frac{2}{p-2} + \frac{3}{p} + \frac{2}{p^2} - \frac{7}{2} \cdot \frac{1}{p-1} + \frac{1}{2} \cdot \frac{1}{p-3}$$

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Taking inverse Laplace transform of both sides we have,

$$y(t) = 3L^{-1}\left\{\frac{1}{p-1}\right\} - 2L^{-1}\left\{\frac{1}{p-2}\right\} + 3L^{-1}\left\{\frac{1}{p}\right\} + 2L^{-1}\left\{\frac{1}{p^2}\right\} - \frac{7}{2}L^{-1}\left\{\frac{1}{p-1}\right\} + \frac{1}{2}L^{-1}\left\{\frac{1}{p-3}\right\}$$

$$\text{or, } y(t) = -\frac{1}{2}e^t - 2e^{2t} + 3 + 2t + \frac{1}{2}e^{3t} = \frac{1}{2}(e^{3t} - e^t) - 2e^{2t} + 2t + 3$$

which is the required solution of the given differential equation.

**22.** Solve the following system of simultaneous differential equations using Laplace transform :

$$\frac{dx}{dt} - y = 0 \text{ and } \frac{dy}{dt} + x = 0 \text{ given that } x = 0 \text{ and } y = 1 \text{ at } t = 0.$$

**Solution** Here the given system of differential equation is :

$$\frac{dx}{dt} - y = 0 \quad \dots (1)$$

$$\text{and } \frac{dy}{dt} + x = 0 \quad \dots (2)$$

Taking the Laplace transform of (1) we have,

$$L\left\{\frac{dx}{dt}\right\} - L\{y\} = L\{0\}$$

$$\text{or, } pL\{x\} - x(0) - L\{y\} = 0$$

$$\text{or, } p\bar{x} - 0 - \bar{y} = 0 \quad [\text{where } \bar{x} = L\{x\}, \bar{y} = L\{y\} \text{ and } x(0) = 0, \text{ given}]$$

$$\text{or, } \bar{y} = p\bar{x} \quad \dots (3)$$

Again taking the Laplace transform of (2) we have,

$$L\left\{\frac{dy}{dt}\right\} + L\{x\} = L\{0\}$$

$$\text{or, } pL\{y\} - y(0) + L\{x\} = 0$$

$$\text{or, } p\bar{y} - 1 + \bar{x} = 0 \quad [\text{since } y(0) = 1, \text{ given}]$$

$$\text{or, } p^2\bar{x} - 1 + \bar{x} = 0 \quad [\text{using (3)}]$$

$$\text{or, } \bar{x} = \frac{1}{1+p^2}$$

Taking inverse Laplace transform, we have,

$$x(t) = L^{-1}\left\{\frac{1}{1+p^2}\right\} = \sin t$$

Again from (3) we have,

$$\bar{y} = p\bar{x} = \frac{p}{1+p^2}$$

Taking inverse Laplace transform, we have,

$$y(t) = L^{-1}\left\{\frac{p}{1+p^2}\right\} = \cos t$$

Hence the required solution of the given differential equation is :  $x(t) = \sin t, y(t) = \cos t$ .

**23.** Solve the following system of simultaneous differential equations using Laplace transform :

$$\frac{dx}{dt} + y = \sin t \text{ and } \frac{dy}{dt} + x = \cos t \text{ given that } x(0) = 2 \text{ and } y(0) = 0. \quad \dots (1)$$

**Solution** Here the given system of simultaneous differential equation is :

$$\frac{dx}{dt} + y = \sin t \quad \dots (1)$$

$$\text{and } \frac{dy}{dt} + x = \cos t \quad \dots (2)$$

Taking Laplace transform of (1) we have,

$$L\left\{\frac{dx}{dt}\right\} + L\{y\} = L\{\sin t\} \text{ or, } pL\{x\} - x(0) + L\{y\} = \frac{1}{1+p^2}$$

$$\text{or, } p\bar{x} + \bar{y} - 2 = \frac{1}{1+p^2} \text{ [where } \bar{x} = L\{x\}, \bar{y} = L\{y\} \text{ and } x(0) = 2, \text{ given]}$$

$$\text{or, } \bar{y} = 2 - p\bar{x} + \frac{1}{1+p^2} \quad \dots (3)$$

Again taking Laplace transform of (2) we have,

$$L\left\{\frac{dy}{dt}\right\} + L\{x\} = L\{\cos t\}$$

$$\text{or, } pL\{y\} - y(0) + L\{x\} = \frac{p}{1+p^2}$$

$$\text{or, } p\bar{y} - 0 + \bar{x} = \frac{p}{1+p^2} \text{ [since } y(0) = 0, \text{ given]}$$

$$\text{or, } p\left[2 - p\bar{x} + \frac{1}{1+p^2}\right] + \bar{x} = \frac{p}{1+p^2} \text{ [using (3)]}$$

$$\text{or, } (1-p^2)\bar{x} + 2p + \frac{p}{1+p^2} = \frac{p}{1+p^2}$$

$$\text{or, } \bar{x} = \frac{2p}{p^2-1} = \frac{1}{p-1} + \frac{1}{p+1} \quad \dots (4)$$

Taking inverse Laplace transform of (4) we have,

$$x(t) = L^{-1}\left\{\frac{1}{p-1}\right\} + L^{-1}\left\{\frac{1}{p+1}\right\} = e^t + e^{-t} \quad \dots (5)$$

Again using (4) in (3) we have,

$$\bar{y} = 2 - \frac{p}{p-1} - \frac{p}{p+1} + \frac{1}{1+p^2} = \frac{1}{1+p^2} + \frac{1}{p+1} - \frac{1}{p-1} \quad \dots (6)$$

Taking inverse Laplace transform of (6) we have,

$$y = L^{-1}\left\{\frac{1}{1+p^2}\right\} + L^{-1}\left\{\frac{1}{p+1}\right\} - L^{-1}\left\{\frac{1}{p-1}\right\} = \sin t + e^{-t} - e^t \quad \dots (7)$$

Combining (5) and (7), we have the required solution as follows :

$$x(t) = e^t + e^{-t}$$

$$y(t) = \sin t + e^{-t} - e^t$$

**24.** Find the general solution of  $(D^2 + a^2)y = 0$  and verify it.

**Solution** Here the given differential equation is  $(D^2 + a^2)y = 0$  ... (1)

Taking Laplace transform of both sides of (1) we have

$$L\{D^2y\} + a^2 L(y) = 0 \text{ or, } [p^2 L(y) - py(0) - y'(0)] + a^2 L(y) = 0$$

or,  $(p^2 + a^2) L(y) = c_1 p + c_2$  where  $y(0) = c_1$  and  $y'(0) = c_2$

$$\text{or, } L\{y\} = \frac{c_1 p + c_2}{p^2 + a^2} = c_1 \cdot \frac{p}{p^2 + a^2} + c_2 \cdot \frac{1}{p^2 + a^2} \quad \dots (2)$$

Now taking inverse Laplace transform of both sides of (2), we have

$$y(t) = c_1 L^{-1}\left\{\frac{p}{p^2 + a^2}\right\} + c_2 L^{-1}\left\{\frac{1}{p^2 + a^2}\right\} = c_1 \cos at + \frac{c_2}{a} \sin at$$

$$= c_1 \cos at + c_3 \sin at, \text{ where } c_3 = \frac{c_2}{a}$$

Hence the required general solution is

$$y(t) = c_1 \cos at + c_3 \sin at, \text{ where } c_1 \text{ and } c_3 \text{ are two arbitrary constants.}$$

**To verify :**

Now differentiating (3) twice with respect to 't'

$$\text{we get } y'' = -a^2 c_1 \cos at - a^2 c_3 \sin at$$

$$\text{Now, } D^2y + a^2y = y'' + a^2y = -a^2 c_1 \cos at - a^2 c_3 \sin at + a^2(c_1 \cos at + c_3 \sin at) = 0,$$

which satisfies (1). So the general solution is  $y = c_1 \cos at + c_3 \sin at$ .

**25.** Solve using Laplace transform :

$$\frac{d^2x}{dt^2} + a^2x = g(t) \text{ given that } x(0) = x'(0) = 0 \text{ and } a > 0.$$

**Solution** Here the given differential equation is

$$\frac{d^2x}{dt^2} + a^2x = g(t) \quad \dots (1)$$

Taking Laplace transform of (1) we have,

$$L\left\{\frac{d^2x}{dt^2}\right\} + a^2 L\{x\} = L\{g(t)\}$$

$$\text{or, } p^2 L\{x\} - px(0) - x'(0) + a^2 L\{x\} = G(p) \quad [\text{where } G(p) = L\{g(t)\}]$$

$$\text{or, } (a^2 + p^2)L\{x\} - p \cdot 0 - 0 = G(p) \quad [\text{using } x(0) = x'(0) = 0]$$

$$\text{or, } L\{x\} = \frac{G(p)}{a^2 + p^2} = \frac{1}{a} \cdot \frac{a}{a^2 + p^2} \cdot G(p)$$

$$\text{i.e., } L\{x\} = \frac{1}{a} L\{\sin at\} L\{g(t)\}$$

Taking inverse Laplace transform, we have,

$$x(t) = \frac{1}{a} L^{-1}\{L\{\sin at\} L\{g(t)\}\} = \frac{1}{a} \int_0^t \sin a(t-x)g(x)dx \quad [\text{using the convolution theorem}]$$

which is the required solution of the given differential equation.

**26.** // Solve the following differential equation by Laplace transform :

$$(D^2 - 2aD + a^2)x(t) = f(t) \text{ where } D \equiv \frac{d}{dt}.$$

**Solution** Here the given differential equation is :

$$(D^2 - 2aD + a^2)x = f(t) \quad \dots (1)$$

Taking Laplace transform of both sides of (1) we have,

$$L[D^2x] - 2aL[Dx] + a^2L[x] = L[f(t)]$$

$$\text{or, } p^2L[x] - px(0) - x'(0) - 2a[pL[x] - x(0)] + a^2L[x] = F(p) \text{ [where } F(p) = L[f(t)]]$$

$$\text{or, } (p^2 - 2a + a^2)\bar{x} - pC_0 - C_1 + 2aC_0 = F(p)$$

[where  $\bar{x} = L[x]$  and  $x(0) = C_0$  say;  $x'(0) = C_1$ , say]

$$\text{or, } (p - a)^2\bar{x} = F(p) + pC_0 + C_1 - 2aC_0$$

$$\text{or, } \bar{x} = \frac{pC_0}{(p-a)^2} + \frac{C_1 - 2aC_0}{(p-a)^2} + \frac{F(p)}{(p-a)^2} = \frac{C_0}{p-a} + \frac{C_1 - aC_0}{(p-a)^2} + \frac{F(p)}{(p-a)^2}$$

Taking inverse Laplace transform from both sides, we have,

$$\begin{aligned} x(t) &= C_0 L^{-1}\left\{\frac{1}{p-a}\right\} + (C_1 - aC_0)L^{-1}\left\{\frac{1}{(p-a)^2}\right\} + L^{-1}\left\{\frac{F(p)}{(p-a)^2}\right\} \\ &= C_0 e^{at} + (C_1 - aC_0)te^{at} + L^{-1}\{L[f(t)]L[te^{at}]\} \\ &= C_0 e^{at} + (C_1 - aC_0)te^{at} + \int_0^t (t-x)e^{a(t-x)}f(x)dx \text{ [using the convolution theorem]} \\ &= C_0 e^{at} + C_2 te^{at} + e^{at} \int_0^t (t-x)e^{-ax}f(x)dx, \text{ where } C_2 = C_1 - aC_0 \end{aligned}$$

$$\text{i.e., } x(t) = e^{at}[C_0 + C_2 t + \int_0^t (t-x)e^{-ax}f(x)dx]$$

which is the required general solution with  $C_0$  and  $C_2$  are two arbitrary constants.

**27.** // Solve by Laplace transformation :

$$\frac{d^2y}{dx^2} + 6 \frac{dy}{dx} + 10y = 0, y(0) = 1, y\left(\frac{\pi}{4}\right) = \sqrt{2}. \quad [\text{CP 2020}]$$

**Solution** Here the given differential equation is

$$\frac{d^2y}{dx^2} + 6 \frac{dy}{dx} + 10y = 0 \quad \dots (1)$$

Taking Laplace transform of both sides of (1), we have

$$L\left\{\frac{d^2y}{dx^2} + 6 \frac{dy}{dx} + 10y\right\} = L\{0\}$$

$$\text{or, } L\left\{\frac{d^2y}{dx^2}\right\} + 6L\left\{\frac{dy}{dx}\right\} + 10L\{y\} = 0 \text{ [using linearity property]}$$

$$\text{or, } \{p^2L\{y\} - py(0) - y'(0)\} + 6\{pL\{y\} - y(0)\} + 10L\{y\} = 0$$

[since  $L[f^{(n)}(t)] = p^n L\{f(t)\} - p^{n-1}f(0) - p^{n-2}f'(0) - \dots - f^{(n-1)}(0)$ ]

$$\text{or, } (p^2 + 6p + 10)L\{y\} - p \cdot 1 - a - 6 \cdot 1 = 0 \text{ [since } y(0) = 1, \text{ given and } y'(0) = a, \text{ say]}$$

$$\text{or, } L\{y\} = \frac{p+a+6}{p^2+6p+10} = \frac{(p+3)+(a+3)}{(p+3)^2+1}$$

$$\begin{aligned} \text{Hence } y(x) &= L^{-1}\left\{\frac{(p+3)+(a+3)}{(p+3)^2+1}\right\} = e^{-3x}L^{-1}\left\{\frac{p+a+3}{p^2+1}\right\} \quad [\text{By first shifting property}] \\ &= e^{-3x}\left[L^{-1}\left\{\frac{p}{p^2+1}\right\} + (a+3)L^{-1}\left\{\frac{1}{p^2+1}\right\}\right] = e^{-3x}[\cos x + (a+3)\sin x] \end{aligned}$$

To determine  $a$ , we have from above,

$$y\left(\frac{\pi}{4}\right) = e^{-\frac{3\pi}{4}}\left[\cos\frac{\pi}{4} + (a+3)\sin\left(\frac{\pi}{4}\right)\right] = \sqrt{2} \quad [\text{Using the boundary condition}]$$

$$\text{or, } a+4 = 2e^{\frac{3\pi}{4}} \text{ giving } a = 2e^{\frac{3\pi}{4}} - 4$$

$$\text{Hence the required solution is : } y(x) = e^{-3x}[\cos x + (2e^{\frac{3\pi}{4}} - 4)\sin x]$$

**28.** Find  $L^{-1}\left\{\frac{4}{s+1} + \frac{6}{(s+1)^2} + \frac{3}{(s+1)^4}\right\}$  and hence solve  $(D^2 + 2D + 1)y = 3te^{-t}$ , given  $y = 4$ ,  $Dy = 2$  when  $t = 0$  and  $D \equiv \frac{d}{dt}$ . [CP 2020]

**Solution** Using the first shifting property, we have,

$$\begin{aligned} L^{-1}\left\{\frac{4}{s+1} + \frac{6}{(s+1)^2} + \frac{3}{(s+1)^4}\right\} &= e^{-t}L^{-1}\left\{\frac{4}{s} + \frac{6}{s^2} + \frac{3}{s^4}\right\} = e^{-t}\left[4L^{-1}\left(\frac{1}{s}\right) + 6L^{-1}\left\{\frac{1}{s^2}\right\} + 3L^{-1}\left\{\frac{1}{s^4}\right\}\right] \\ &= e^{-t}\left[4 \cdot 1 + 6t + 3 \cdot \frac{t^3}{6}\right] \quad [\text{since } L^{-1}\left\{\frac{n!}{p^{n+1}}\right\} = t^n] \\ &= \frac{e^{-t}}{2}[t^3 + 12t + 8] \end{aligned}$$

$$\text{Therefore } L^{-1}\left\{\frac{4}{s+1} + \frac{6}{(s+1)^2} + \frac{3}{(s+1)^4}\right\} = \frac{e^{-t}}{2}[t^3 + 12t + 8] \quad \dots (1)$$

Now, the given differential equation is :

$$(D^2 + 2D + 1)y = 3te^{-t}$$

Taking Laplace transform of both sides of (1) we have,

$$L(D^2 + 2D + 1)y = L(3te^{-t}) \quad \text{or, } L(D^2y) + 2L(Dy) + L(y) = -3 \frac{d}{ds}\left(\frac{1}{s+1}\right)$$

$$\text{or, } \{s^2L(y) - sy(0) - Dy(0)\} + 2\{sL(y) - y(0)\} + L(y) = \frac{3}{(s+1)^2}$$

$$\text{or, } (s^2 + 2s + 1)L(y) - 4s - 2 - 8 = \frac{3}{(s+1)^2} \quad [\text{Using initial conditions}]$$

$$\text{or, } (s+1)^2L(y) = 4(s+1) + 6 + \frac{3}{(s+1)^2}$$

$$\text{or, } L(y) = \frac{4}{s+1} + \frac{6}{(s+1)^2} + \frac{3}{(s+1)^4}$$

$$\text{Hence } y(t) = L^{-1}\left\{\frac{4}{s+1} + \frac{6}{(s+1)^2} + \frac{3}{(s+1)^4}\right\} = \frac{e^{-t}}{2}[t^3 + 12t + 8] \quad [\text{using (1)}]$$

which is the required solution of the given differential equation.